


**MÉCANISMES NON LINÉAIRES DANS DES
DISPOSITIFS MEMS POUR LA RÉCUPÉRATION
D'ÉNERGIE**



**ON THE USE OF NON-LINEAR MEMS FOR ENERGY
HARVESTING**

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OUTLINE



- Energy Harvesting Overview
- Non-linear mechanisms & energy harvesting
 - Principle
 - Modeling
 - SDE-Matlab simulations
- The micro-machined device
 - Fabrication
 - SDE-Matlab simulations
- Experimental results
 - Set-up
 - Positioning the permanent magnet
 - Response @ optimal position
 - Transient response vs simulation

ENERGY HARVESTING OVERVIEW




- Energy harvesting materials and systems have emerged as a prominent research area...
- Here we focus on the problem of harvesting energy from ambient mechanical vibrations

Embedded sensor nodes

Autonomous sensors


Smart systems

Recharging batteries




Source: Seiko Watch Corporation

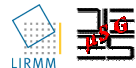
Courtesy of Greg Ehlers/Simon Fraser University



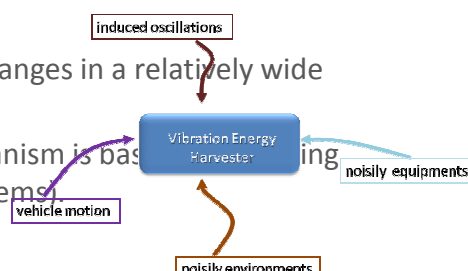
courtesy of Perpetua Power Source Technologies

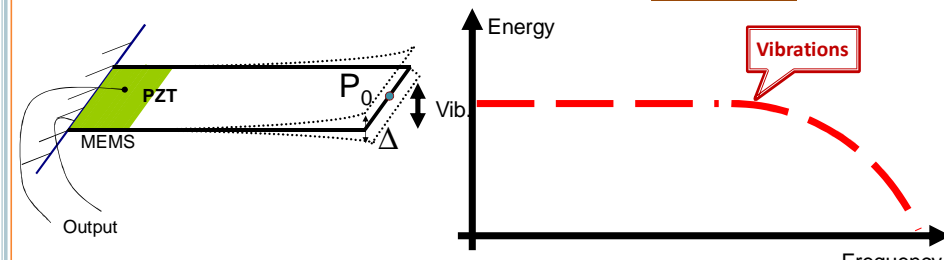


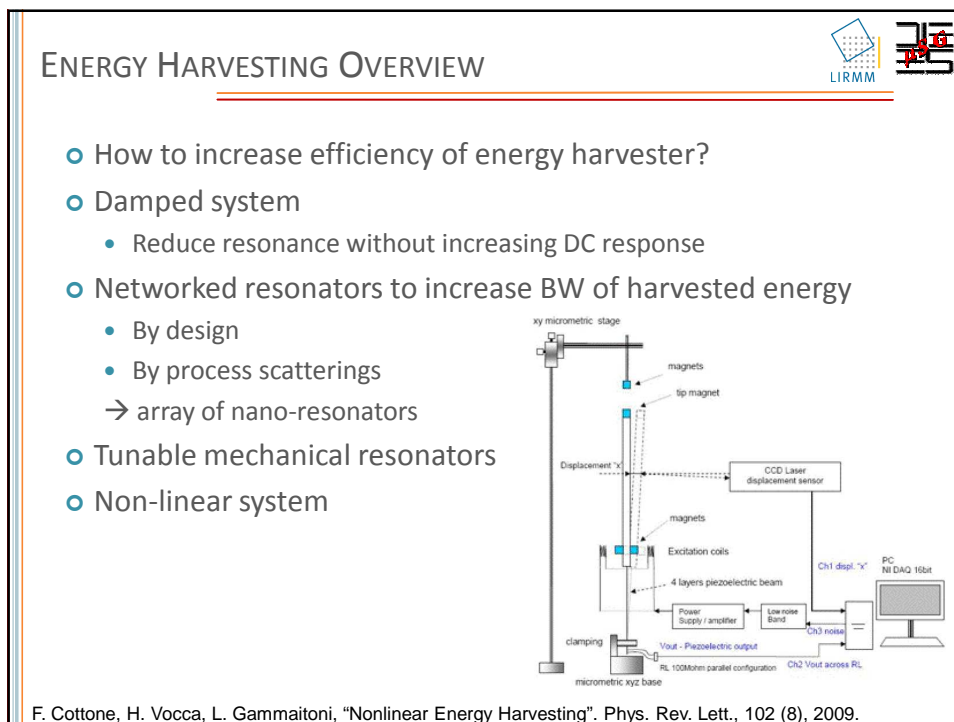
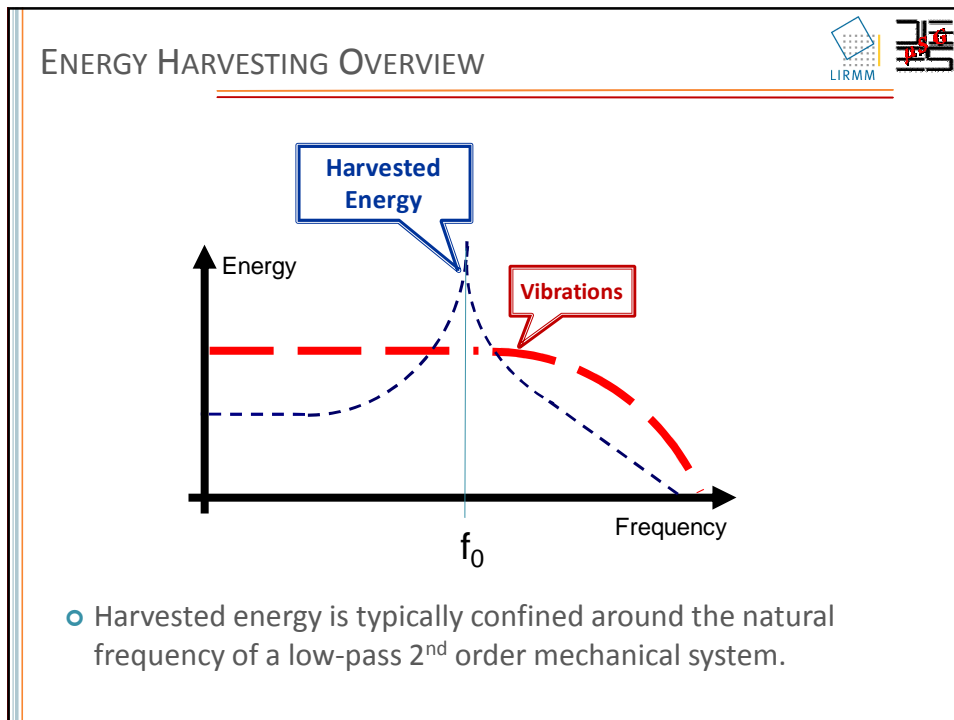
ENERGY HARVESTING OVERVIEW



- In the vast majority of cases the ambient vibrations come in a vast variety of forms.
- Energy of ambient vibrations ranges in a relatively wide spectrum of frequencies
- A classical transduction mechanism is based on piezoelectricity using mechanical bodies (linear systems)







OUTLINE

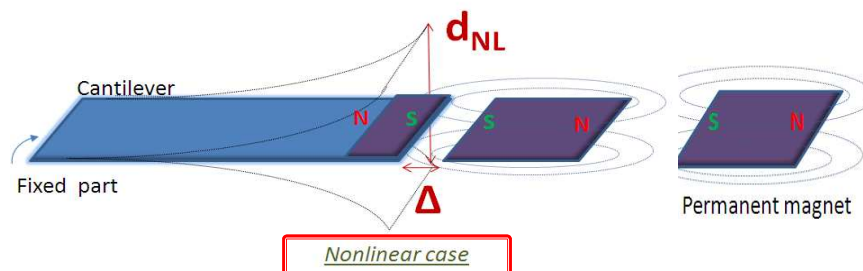



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NON-LINEAR MECHANISMS & ENERGY HARVESTING

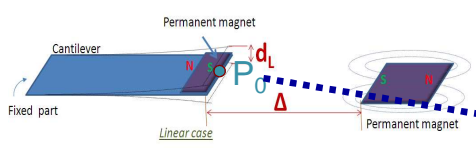


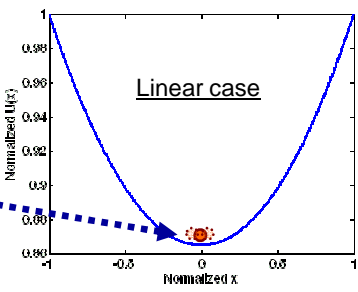
- The idea is to consider not only the device vibrations but also the nonlinear behavior of a bi-stable system to increase collected energy.
- How to obtain such a system?
 - Example: the non-linear bi-stable cantilever



NON-LINEAR MECHANISMS & ENERGY HARVESTING 

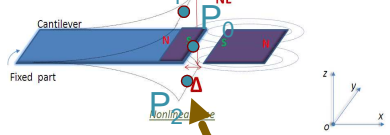
o Principle of operation

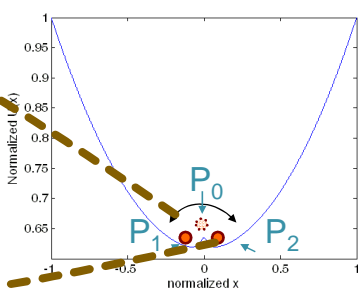





Linear case

P₀ is an unstable state !





NON-LINEAR MECHANISMS & ENERGY HARVESTING 

o Modeling: the nonlinear system has been modeled considering a classical mass-spring-damper system, with an additive nonlinear term described by a bi-stable (double well) potential energy function. x represents the displacement of the beam, while, Ψ represents the nonlinear term that includes the elastic constant term k :

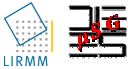
$$m\ddot{x} + d\dot{x} + \psi = f(t)$$

Mass of the beam
Damping coefficient
Stochastic source

$$\psi \triangleq \frac{\partial U(x)}{\partial x} = U'(x)$$

$$U(x) = kx^2 + (ax^2 + b\Delta^2)^{-\frac{3}{2}} + c\Delta^2$$

$$\Psi = U(x)' = \frac{\partial}{\partial x} \left[kx^2 + (ax^2 + b\Delta^2)^{-\frac{3}{2}} + c\Delta^2 \right] = 2kx + \left[\frac{-\frac{3}{2}(ax^2 + b\Delta^2)^{-\frac{5}{2}} 2ax}{(ax^2 + b\Delta^2)^{\frac{3}{2}}} \right] = -3ax(ax^2 + b\Delta^2)^{-\frac{5}{2}} + 2kx$$

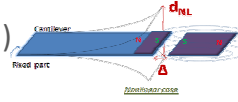
LIRMM 

NON-LINEAR MECHANISMS & ENERGY HARVESTING

- Modeling: nonlinear dynamical model (Itô's form)

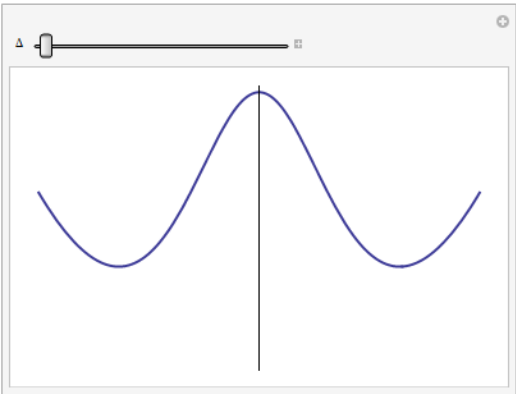
$$dx_1 = x_2 dt = f_1(x) dt$$

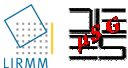
$$dx_2 = \left[-\frac{d}{m} x_2 + \frac{3\alpha x_1 (ax_1^2 + b\Delta^2) - \frac{m}{2}}{m} - \frac{2kx_1}{m} \right] dt + \frac{\sigma}{m} dW_t = f_2(x) dt + g_2(x) dW_t$$



W_t : Wiener process
 σ : std of the noise source

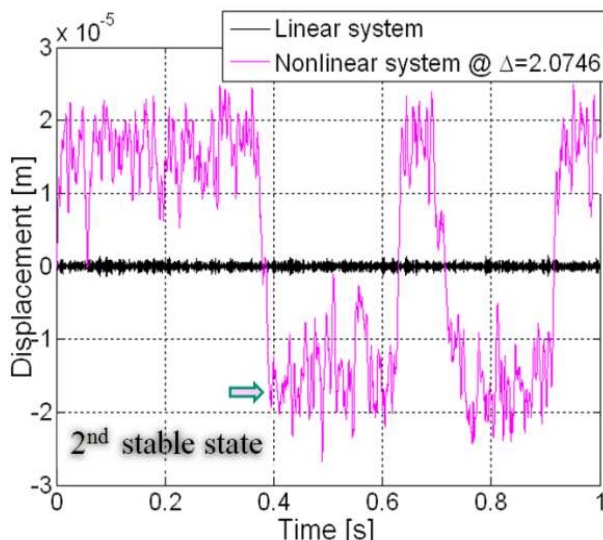
Nonlinear Term (Δ)



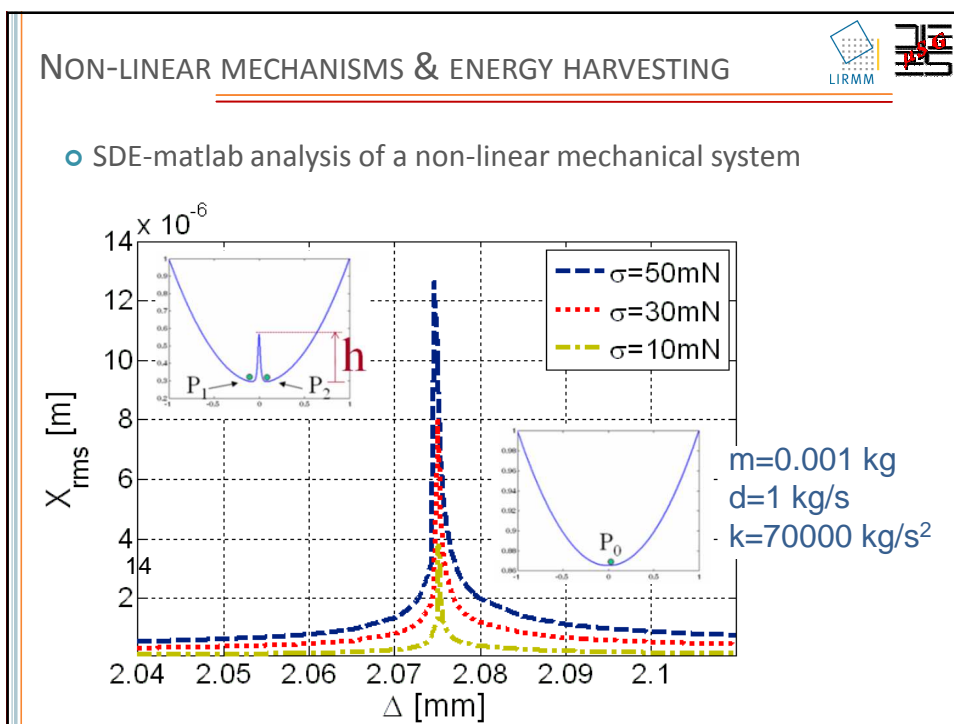
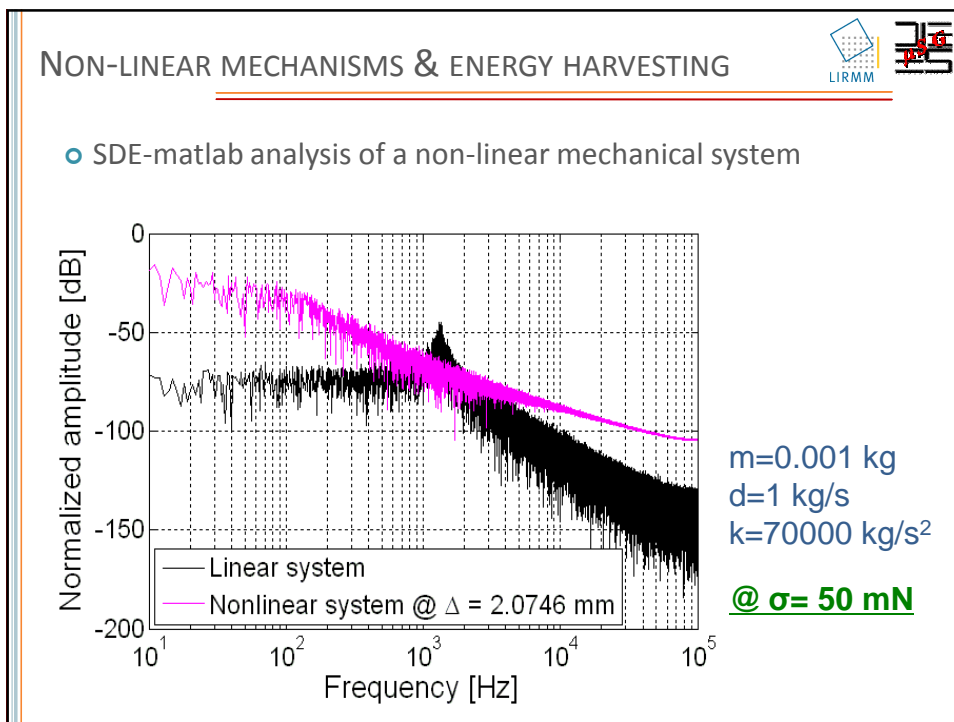
LIRMM 

NON-LINEAR MECHANISMS & ENERGY HARVESTING

- SDE-matlab analysis of a non-linear mechanical system



$m=0.001$ kg
 $d=1$ kg/s
 $k=70000$ kg/s²
@ $\sigma=50$ mN



OUTLINE

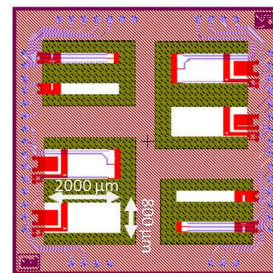
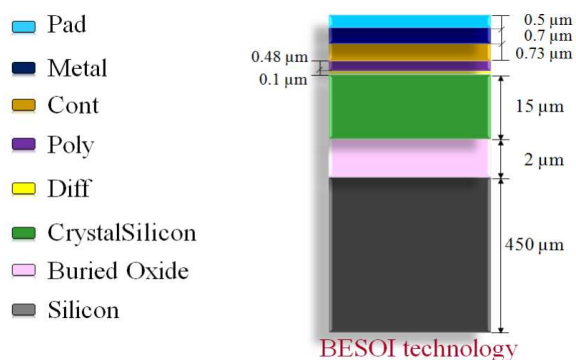


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THE MICRO-MACHINED DEVICE



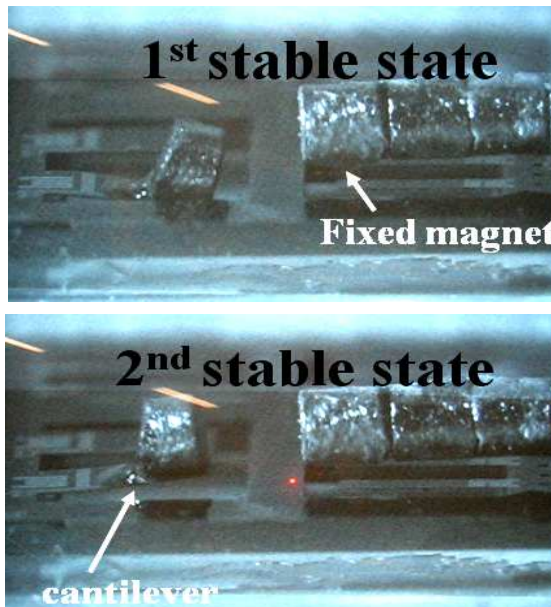
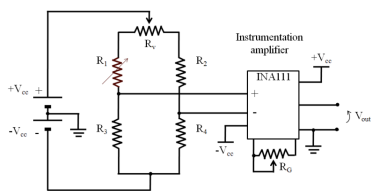
- SOI wafer: 15 μm c-Si layer, 450 μm carrier substrate, 2 μm buried oxide
- Front and back side DRIE etching technique
- Fabrication: CNM, Barcelona, Spain



THE MICRO-MACHINED DEVICE



- Bi-stable SOI cantilever beam
 - After gluing a magnet, bi-stable behavior is obtained
 - Displacement is electrically-measured through strain gauges

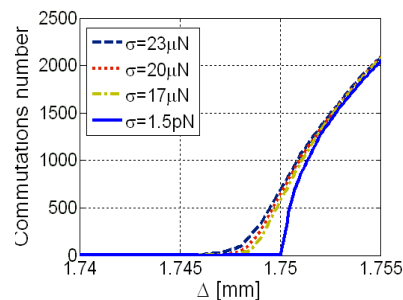
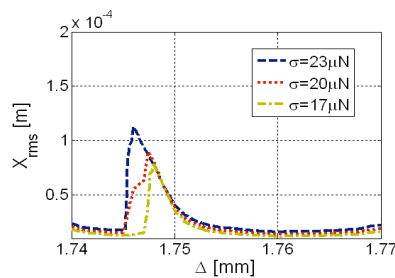
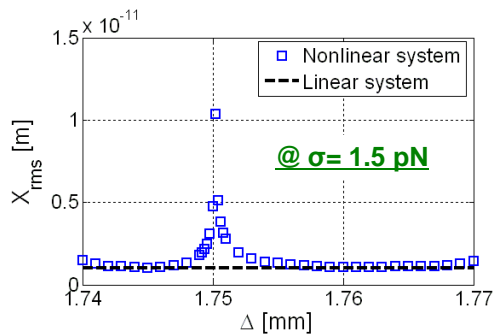


THE MICRO-MACHINED DEVICE



- SDE-matlab analysis of a SOI cantilever beam

$m=1e-8$ kg
 $d=1e-5$ kg/s
 $k=15$ kg/s²



THE MICRO-MACHINED DEVICE

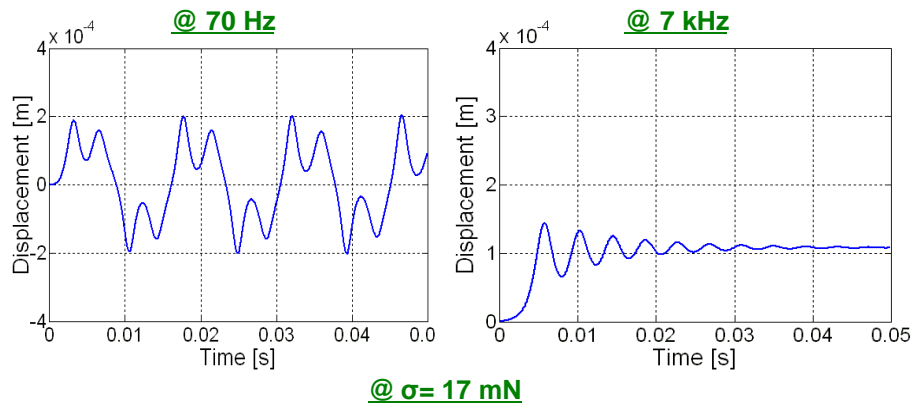


- SDE-matlab analysis of a SOI cantilever beam
 - displacement of the beam excited by a sinusoidal waveform having an amplitude of 17mN

$$m=1e-8 \text{ kg}$$

$$d=1e-5 \text{ kg/s}$$

$$k=15 \text{ kg/s}^2$$



OUTLINE

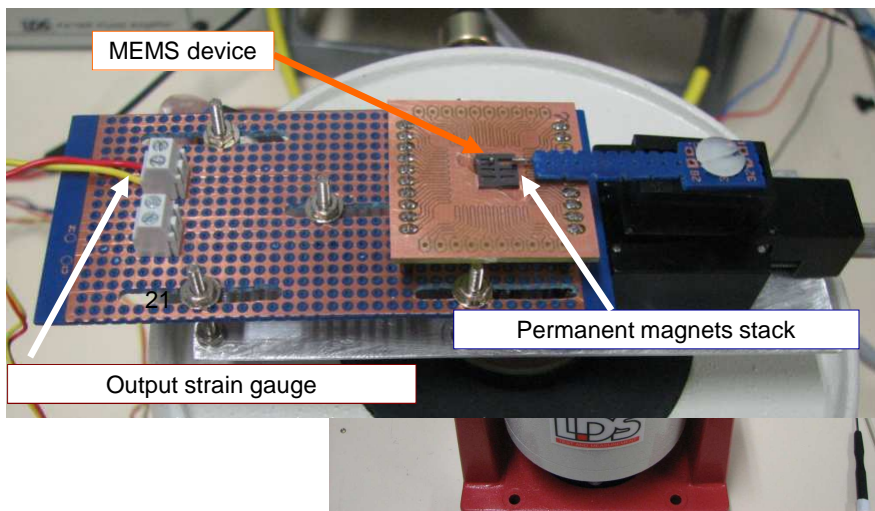


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EXPERIMENTAL RESULTS



Experimental set-up

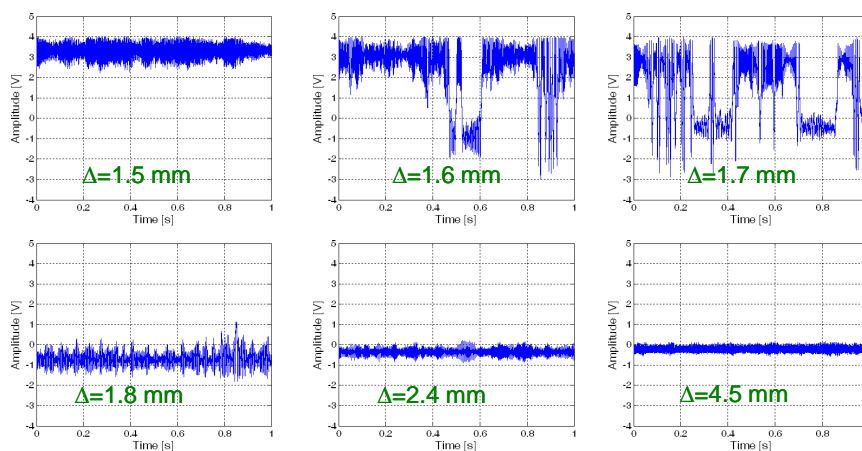


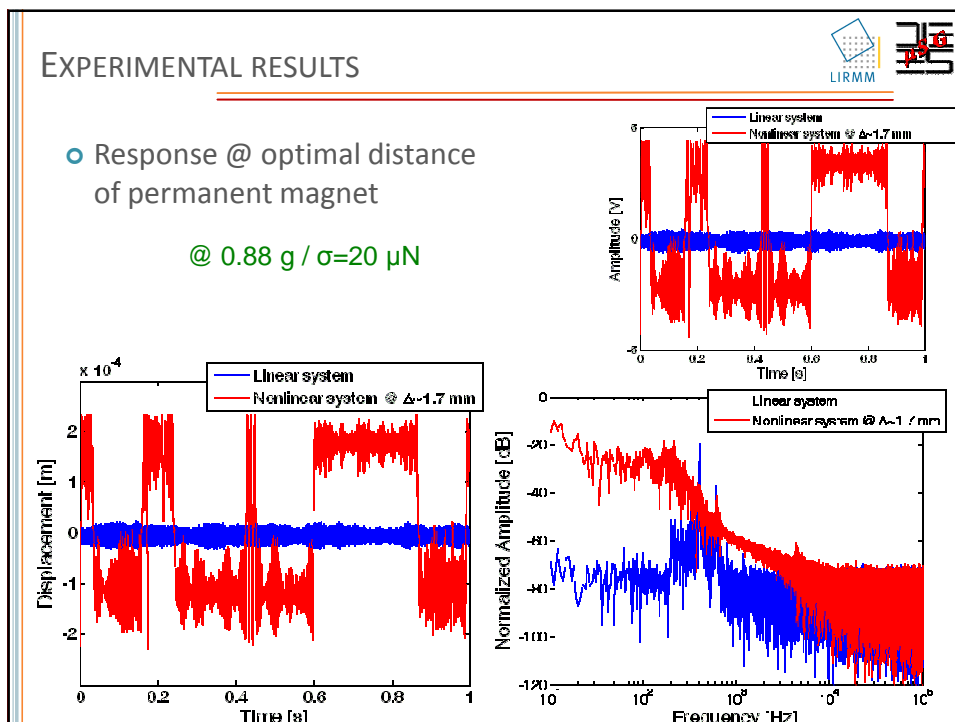
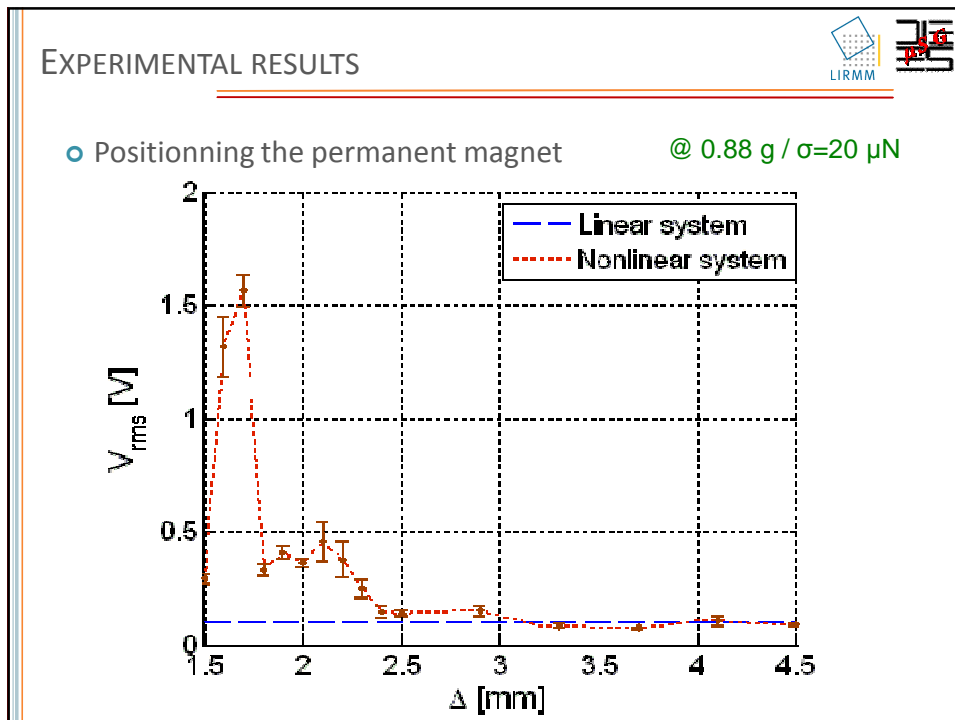
EXPERIMENTAL RESULTS



Positioning the permanent magnet

@ 0.88 g / $\sigma=20 \mu\text{N}$

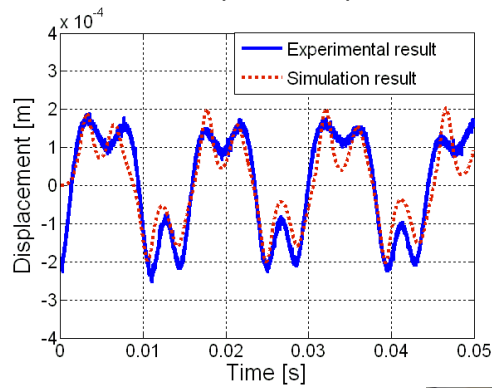




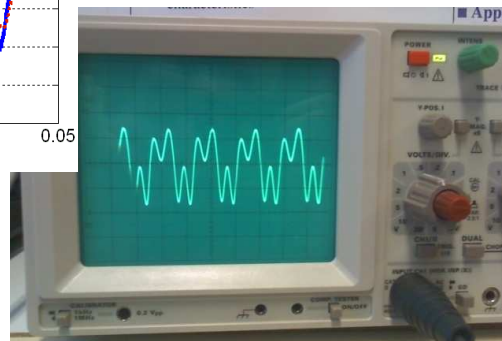
EXPERIMENTAL RESULTS



- Transient response: experimental result vs simulation



@ 70 Hz



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CONCLUSIONS AND FUTURE TRENDS



- Bi-stability seems a promising principle to increase efficiency of energy harvesters
 - A micro-machined BESOI device has been designed and fabricated
 - Modeling vs experimental are in-line
 - Magnet deposition relates to craft arts
 - Very sensitive to magnet positioning
- a micro-machined device with embedded piezoelectric and magnetic foil materials will be realized.

