

(Nearly-)Tight Bounds on the Linearity and Contiguity of Cographs

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EXTENDED ABSTRACT

Introduction. Linearity and contiguity are graph parameters introduced to obtain efficient codings of neighborhoods in graphs, by decomposing each neighborhood as a union of p intervals chosen in one or several orders on the vertices [1]. Indeed, storing an order of the vertices as well as a pair of pointers for each of the p intervals of this order (one pointer for the beginning of the interval and one for the end), with fixed p , allows to store the graph in $O(n)$ space (instead of $O(n + m)$ with adjacency lists) and access the neighborhood of any vertex v in $O(d)$ time (instead of $O(n)$ with adjacency matrices), where d is the degree of v .

More formally, a *closed p -interval-model* of a graph $G = (V, E)$ is a linear order σ on V such that $\forall v \in V, \exists (I_1, \dots, I_p) \in (2^V)^p$ such that $\forall i \in \int 1, p, I_i$ is an interval of σ and $N[v] = \bigcup_{1 \leq i \leq p} I_i$. The *closed contiguity* of G , denoted by $cont(G)$, is the minimum integer p such that there exists a closed p -interval-model of G . A *closed p -line-model* of a graph $G = (V, E)$ is a tuple $(\sigma_1, \dots, \sigma_p)$ of linear orders on V such that $\forall v \in V, \exists (I_1, \dots, I_p) \in (2^V)^p$ such that $\forall i \in \int 1, p, I_i$ is an interval of σ_i and $N[v] = \bigcup_{1 \leq i \leq p} I_i$. The *closed linearity* of G , denoted by $lin(G)$, is the minimum p such that there exists a closed p -line-model of G .

Not much is known about these parameters, which cannot be bounded by a constant even in very restricted graph classes, like interval or permutation graphs [1]. We focus here on the contiguity and linearity of cographs (graphs without induced P_4 subgraphs), whose very constrained structure can be represented by their *cotree*, a rooted tree with two kinds of nodes labeled by P and S , giving a tight upper bound for the asymptotic contiguity of cographs and an upper bound for their linearity. To this aim, we first establish a min-max theorem on the link between the rank of rooted trees and their decompositions into paths.

A min-max theorem on the rank of a tree. The *rank* [2, 3] of a tree T is the maximal height of a complete binary tree obtained from T by edge contractions, that is $rank(T) = \max\{h(T') \mid T' \text{ complete binary tree, minor of } T\}$.

A *path partition* of a tree T is a partition $\{P_1, \dots, P_k\}$ of $V(T)$ such that for any i , the subgraph $T[P_i]$ of T induced by P_i is a path, as shown in Figure 1(a). The *partition tree* of a path partition \mathcal{P} , denoted by $T_p(\mathcal{P})$ and illustrated in Figure 1(b), is the tree whose nodes are P_i 's and where the node of $T_p(\mathcal{P})$ corresponding to P_i is the parent of the node corresponding to P_j iff some node of P_i is the parent in T of the root of P_j . The height of a path partition \mathcal{P} of a tree T , denoted by $h(\mathcal{P})$, is the height $h(T_p(\mathcal{P}))$ of its partition tree. The *path-height* of T is the minimal height of a path partition of T , that is $ph(T) = \min\{h(\mathcal{P}) \mid \mathcal{P} \text{ path partition of } T\}$.

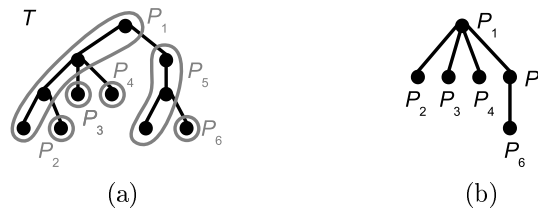


Figure 1: A tree T and a path partition $\mathcal{P} = \{P_1, P_2, P_3, P_4, P_5, P_6\}$ of T (a), as well as the partition tree of \mathcal{P} (b).

